Real-Time Reyes-Style Adaptive Surface Subdivision

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Offline Rendering



- Looks realistic
- Virtually no visible artifacts
- Renders on clusters of CPUs
 - Slow: hours per frame
 - Flexible rendering pipelines

Real-Time Rendering

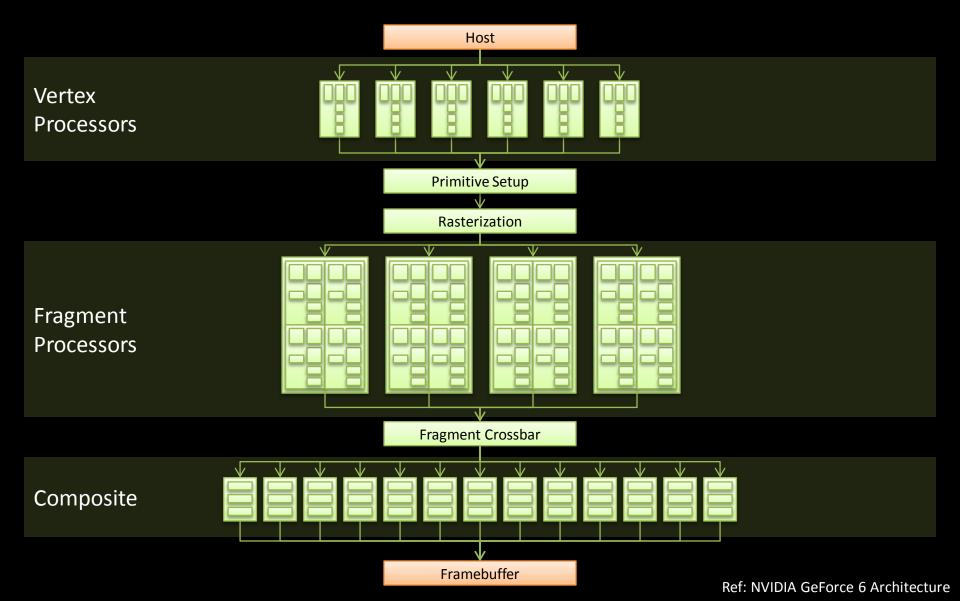


- Looks good enough
- Minor artifacts are OK
- Renders on commodity GPUs
 - Fast: 60+ frames per second
 - Restrictive rendering pipeline

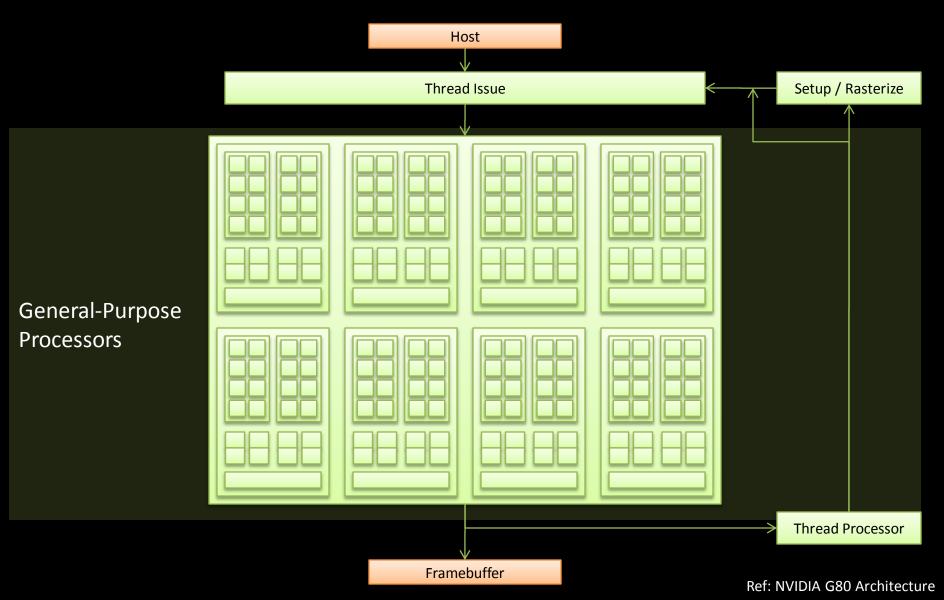
There is a gap

- Geometric complexity
 - From Polygon Meshes to Smooth Surfaces
- Shading complexity
 - From HLSL to RenderMan shaders
- Special Effects
 - Motion Blur, depth-of-field
- Other complex effects
 - Global Illumination, Subsurface scattering, ambient occlusion

But commodity GPUs...



... have changed a lot



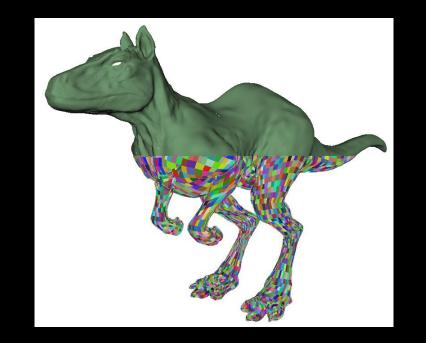
How does this affect things?

- Increased programmability
 - Arbitrary computation
 - Dynamic memory management
 - Irregular data structures
- Flexible Rendering
 - Compute for graphics
 - Offline quality in real-time ?
- But we must be careful

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Anjul Patney and John D. Owens SIGGRAPH Asia 2008 http://graphics.idav.ucdavis.edu/publications/print_pub?pub_id=952

Outline

- Motivation
- Reyes Subdivision algorithm
 - Challenges
 - Parallel formulation
- Subdivision on GPU implementation
 - Issues
 - Solutions
- Results

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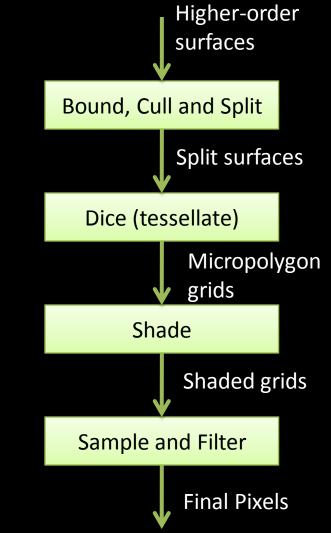
Motivation

- Polygon-based Rendering is insufficient
 - Undesirable artifacts, especially along silhouettes
 - Complicated model representation
 - Model resolution is view-independent
- Can we expect performance from irregular computation on GPUs?
- Can GPUs support completely new pipelines?



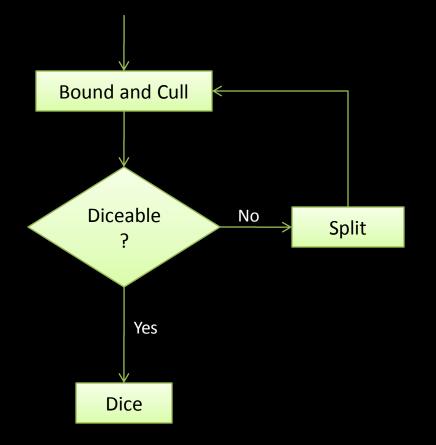
Enter Reyes

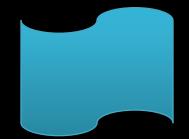
- Industry standard in high-quality rendering
- Forms the architecture beneath RenderMan
- Pipeline features
 - Input: Parametric Surfaces
 - Rendering primitive: 0.5 x 0.5 pixel micropolygons
 - Adaptive tessellation
 - Per-micropolygon programmable shading
 - Stochastic sampling

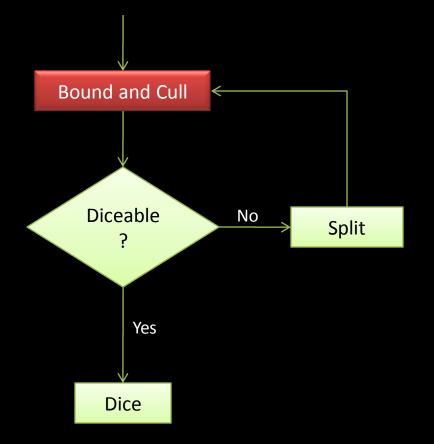


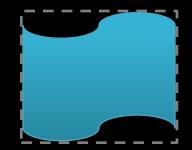
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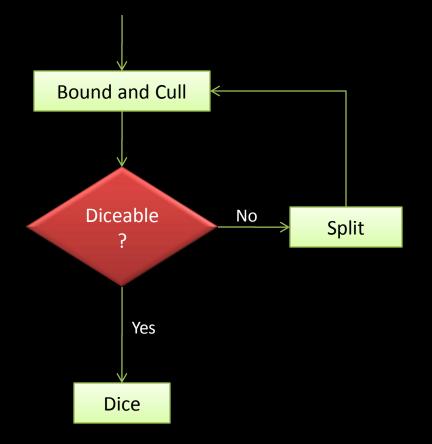
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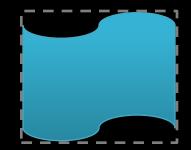


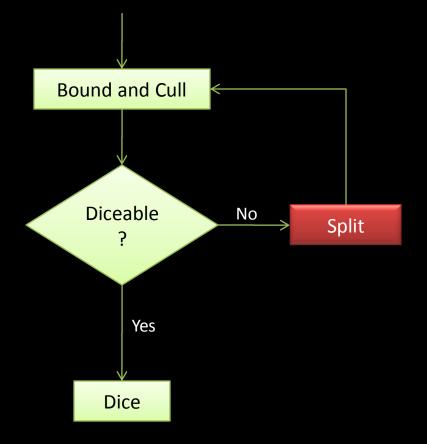


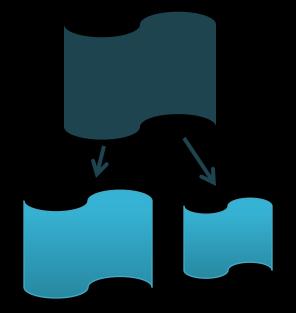


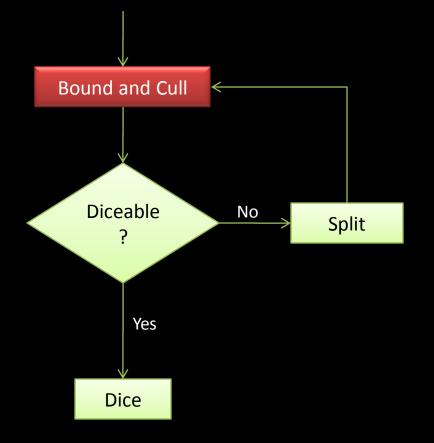


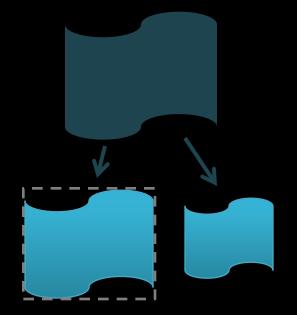


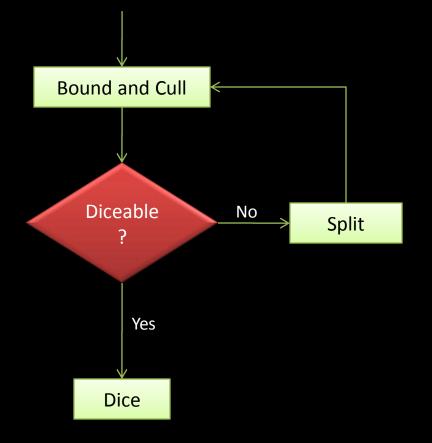


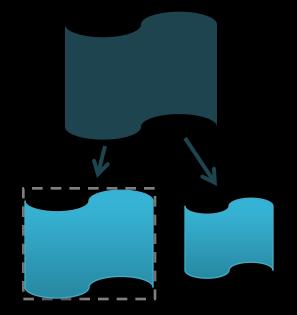


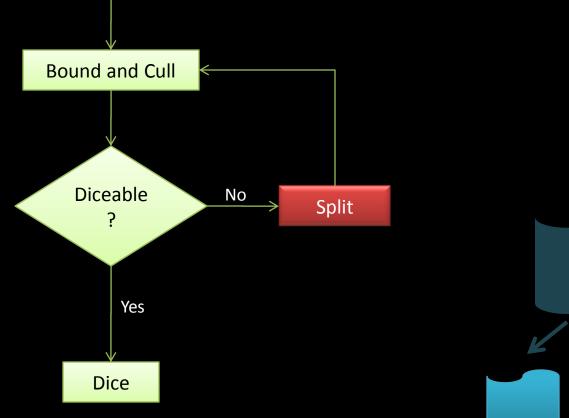


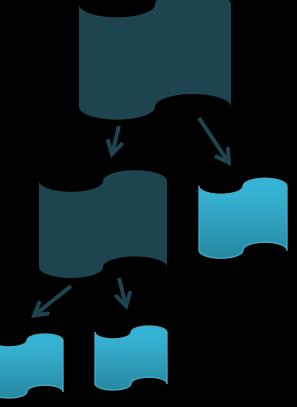


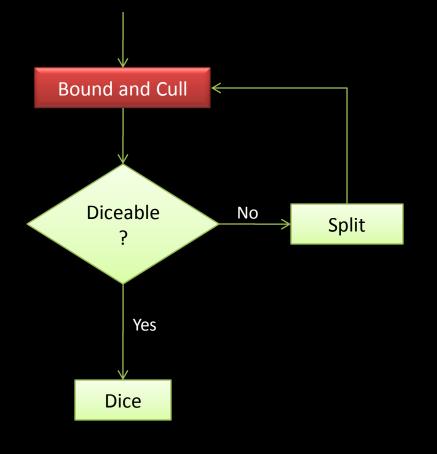


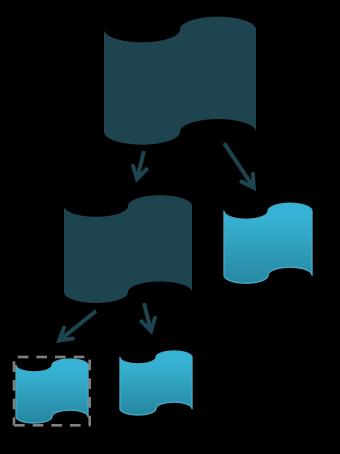


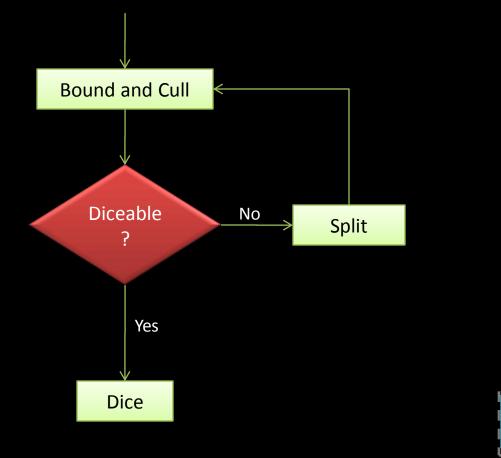


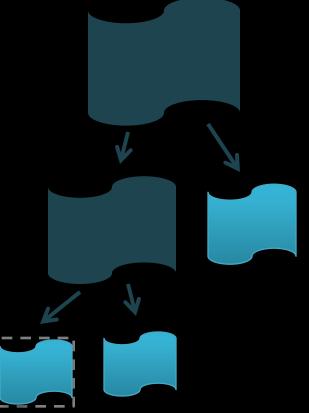


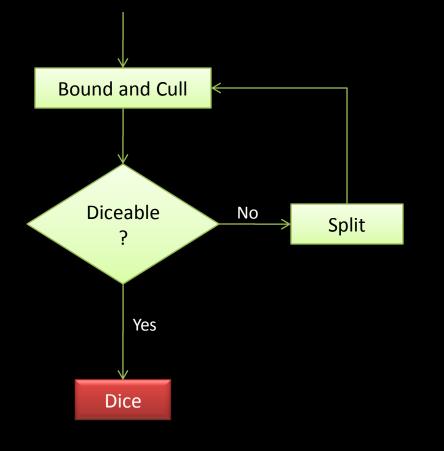


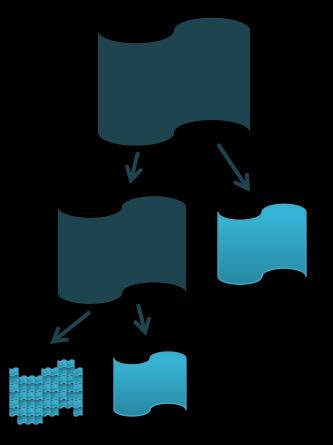


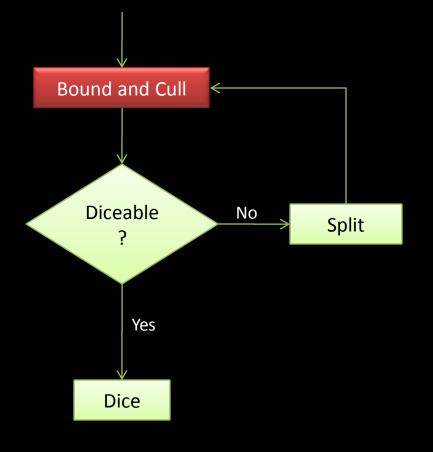


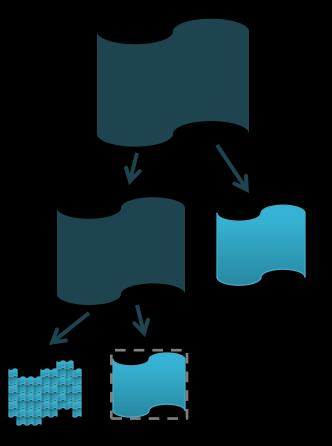


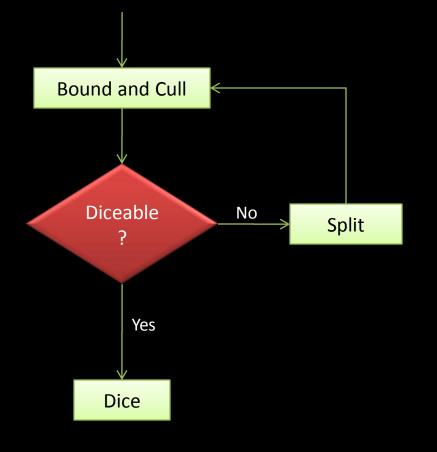


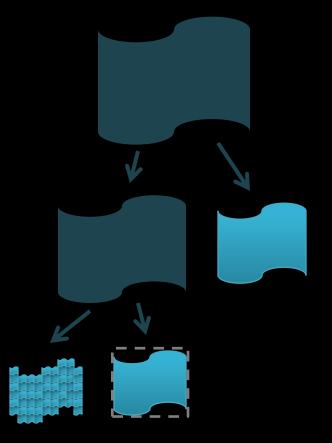


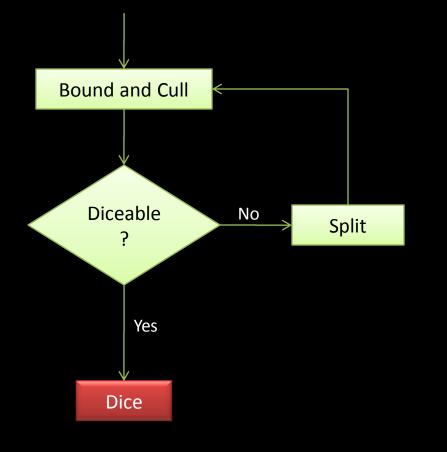


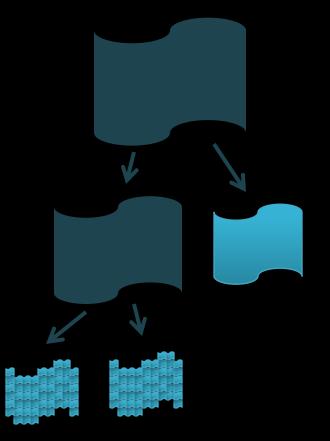


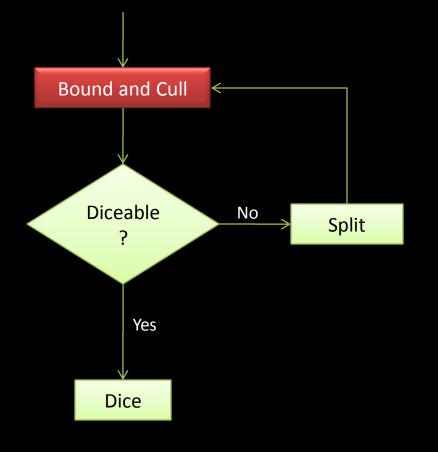


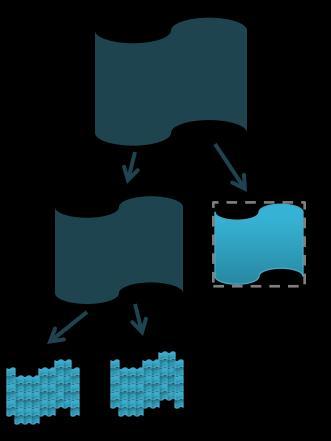


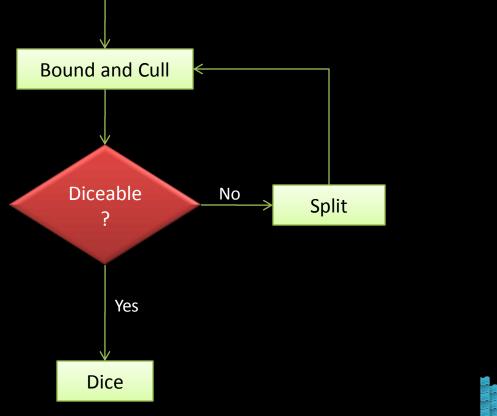


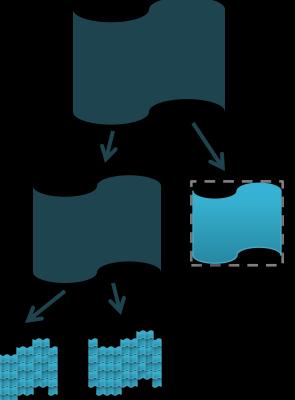


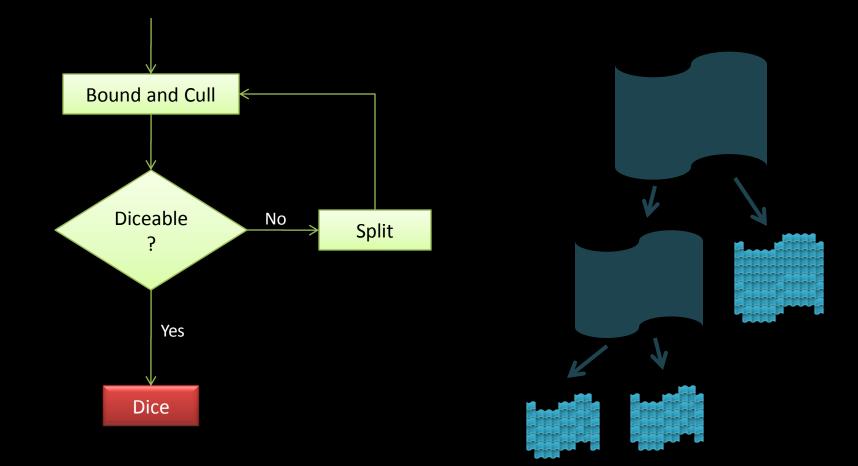












What is bad?

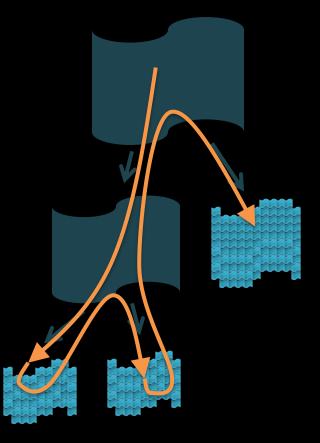
• Depth first subdivision is recursive!

- List of primitives is not static

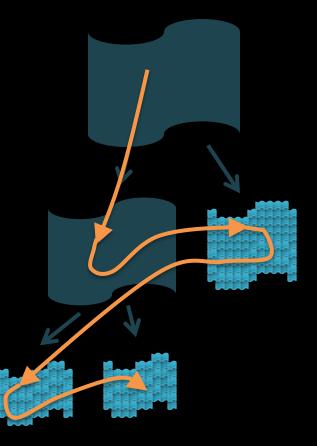
 Cull, split may destroy or generate primitives
- Unbounded memory

Dicing produces a huge number of micropolygons

Can we do this in parallel?



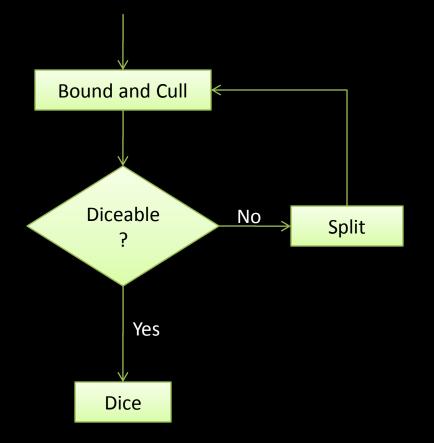
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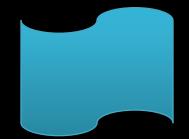


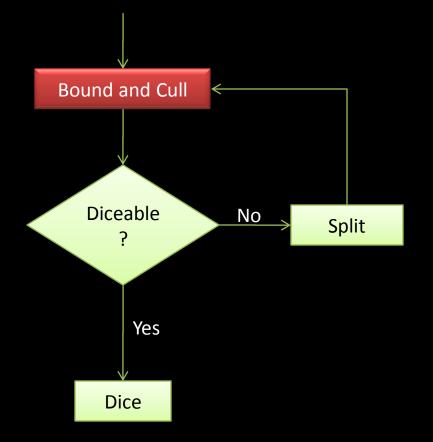
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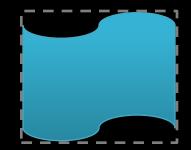
- A lot of independent operations
 - Our simplest model:
 - 5k primitives, 1.2M micropolygons
 - Massively Parallel workload
- Regular Computation
 - Bound/Split/Dice all primitives together
 - SPMD friendly

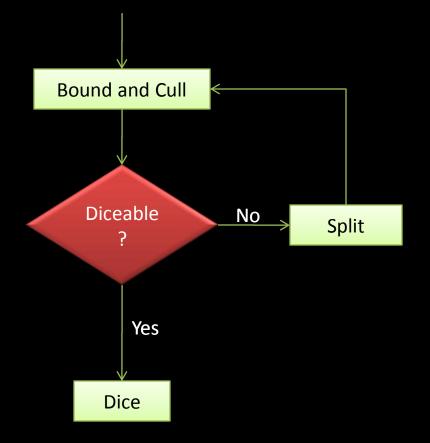
Parallel Reyes Subdivision



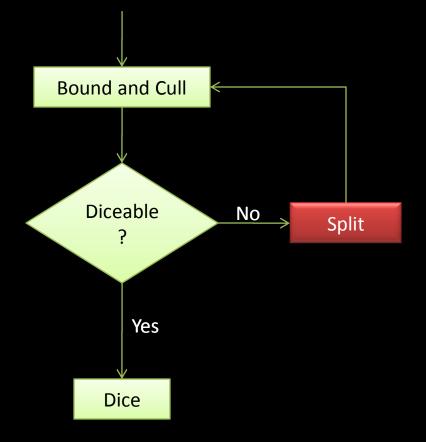


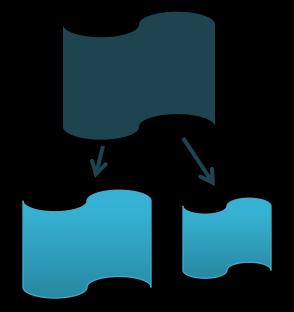


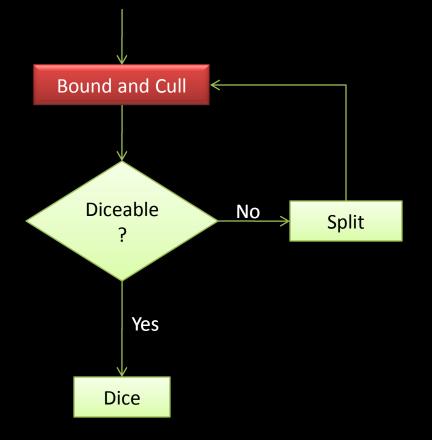


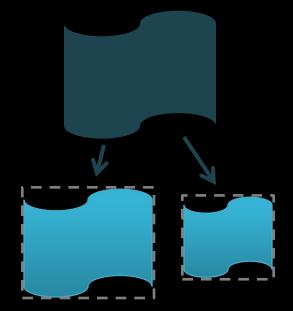


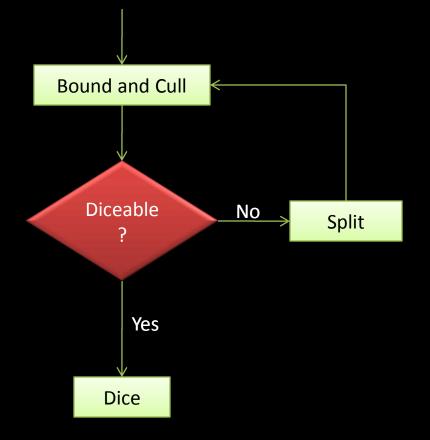


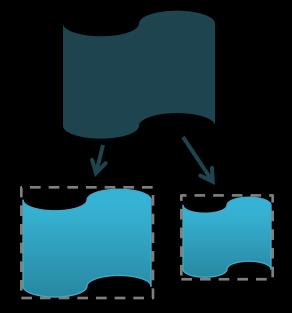


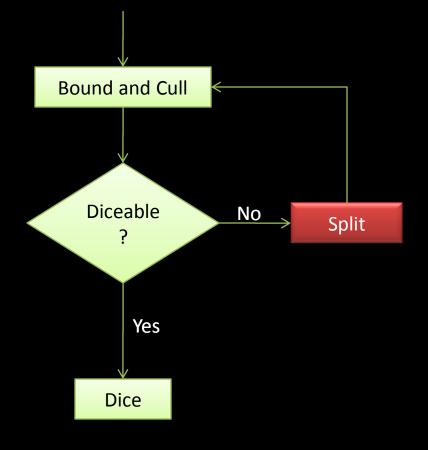


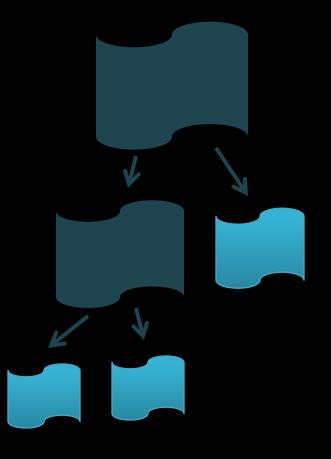


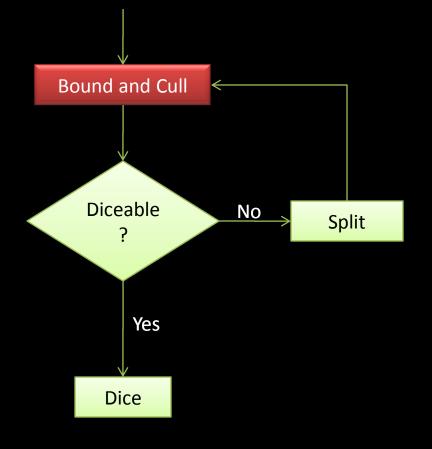


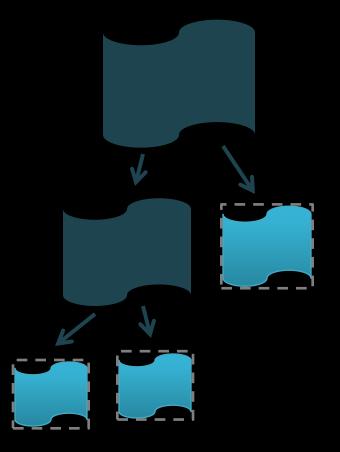


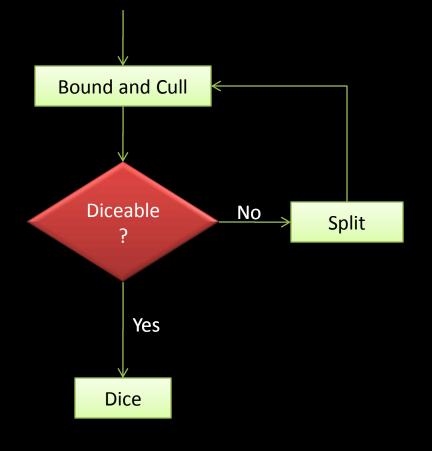


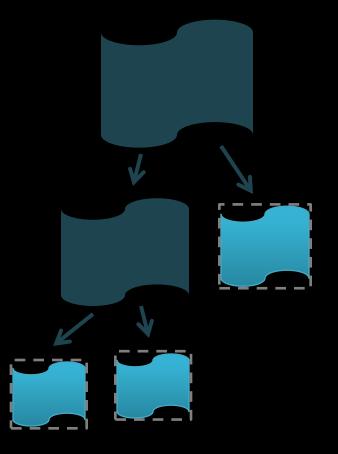


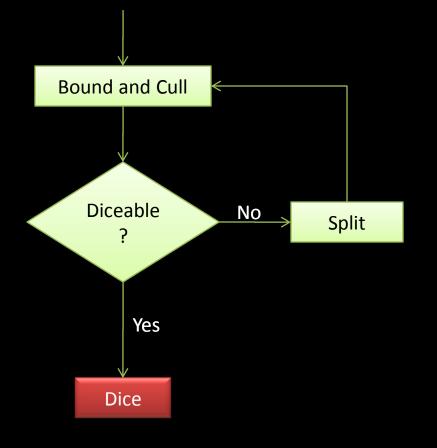


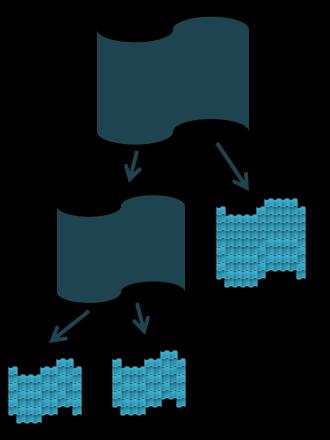




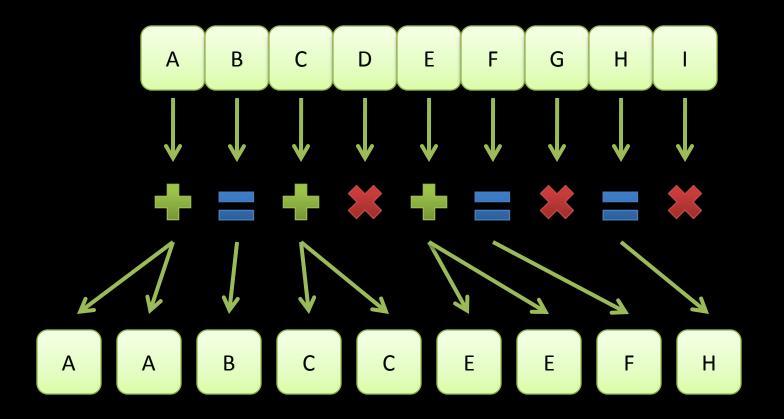








Analogy: A Dynamic Work Queue





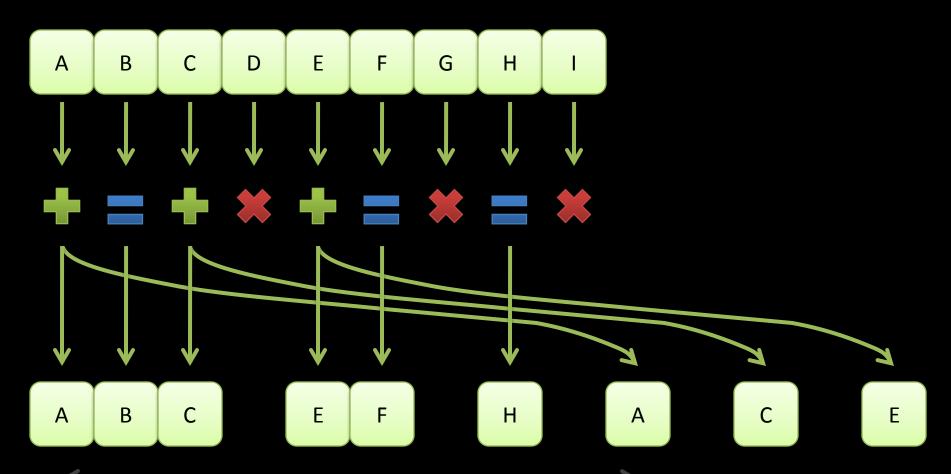
How can we do these efficiently?

• Creating new primitives

– How to dynamically allocate space?

Culling unneeded primitives
 – How to avoid fragmentation?

Our Choice – keep it simple...



A child primitive is offset by the queue length

...and get rid of the holes later

С Ε С В F Н Ε Α Α В С Ε F Н С Ε Α Α

Work-queue stays contiguous

Scan-based compact is fast! (Sengupta '07)

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Platform

- NVIDIA GeForce 8800 GTX
 - 16 SMs, each with 32-wide effective SIMD
 - 16KB shared memory per SM
 - 768 MB total GPU memory, no cache

- NVIDIA CUDA 1.1
 - Grid/Block/Thread programming model
 - OpenGL interface through shared buffers

Implementation Details

- Input primitives Bicubic Bézier Surfaces

 Choice of primitive only affects implementation
- View Dependent Subdivision every frame

 CPU-GPU input transfer only once
 - Suitable for animating control points
- Final micropolygons sent to OpenGL as a VBO

 Flat-shaded and displayed for preview

Kernels Implemented

- Dice
 - Regular, symmetric computation on a highly parallel workload
 - 256 threads per primitive
 - Primitive information in shared memory
- Bound/Split

- Non-trivial to ensure efficiency in implementation

Bound/Split: Efficiency Goals

Memory Coherence

Off-chip memory accesses must be efficient

- Computational Efficiency
 - Hardware SIMD must be maximally utilized

Memory Coherence

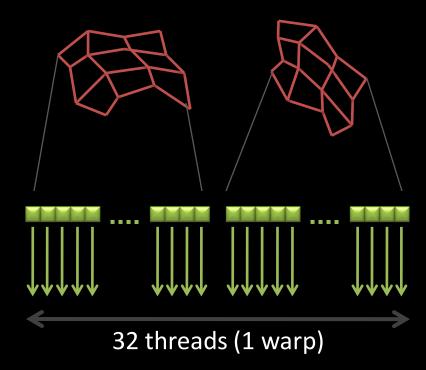
After each iteration, work queue is compacted
 Primitives always contiguous in memory

- Structure-Of-Arrays representation

 Attributes across primitives adjacent in memory
- 99.5% of all accesses were fully coalesced

SIMD Utilization

- Intra-Primitive parallelism
 - A primitive's control points are mostly independent
 - Execution path divergence is negligible
- 16 Threads per primitive
 - Vectorized Bound/Split
 - Use shared memory for communication
- 90.16% of all branches were SIMD coherent

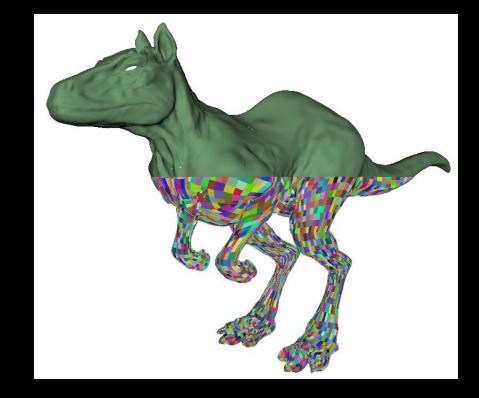


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Results - Killeroo

- 11532 patches → 14426 grids
- 5 levels of subdivision
- Bound/Split: 6.99 ms
- Dice: 7.21 ms
- 4.2 frames per second (subdivision-only: 70)

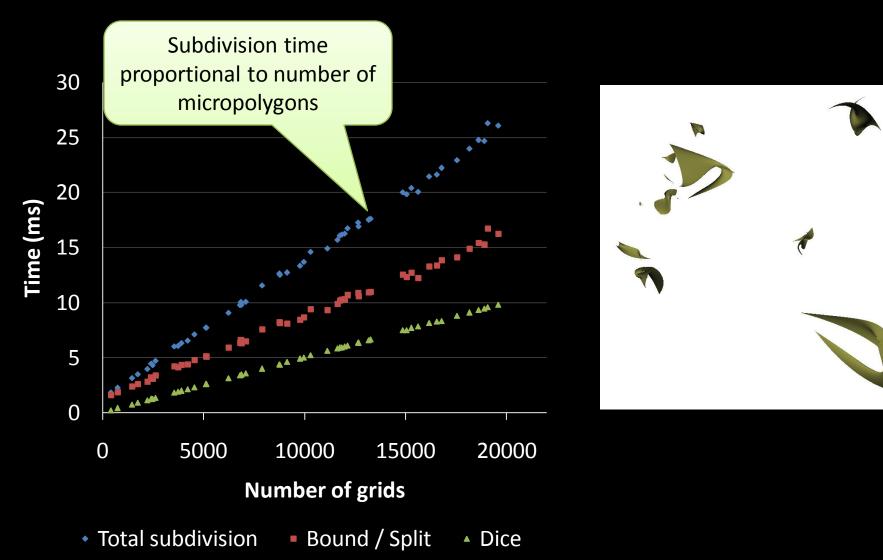


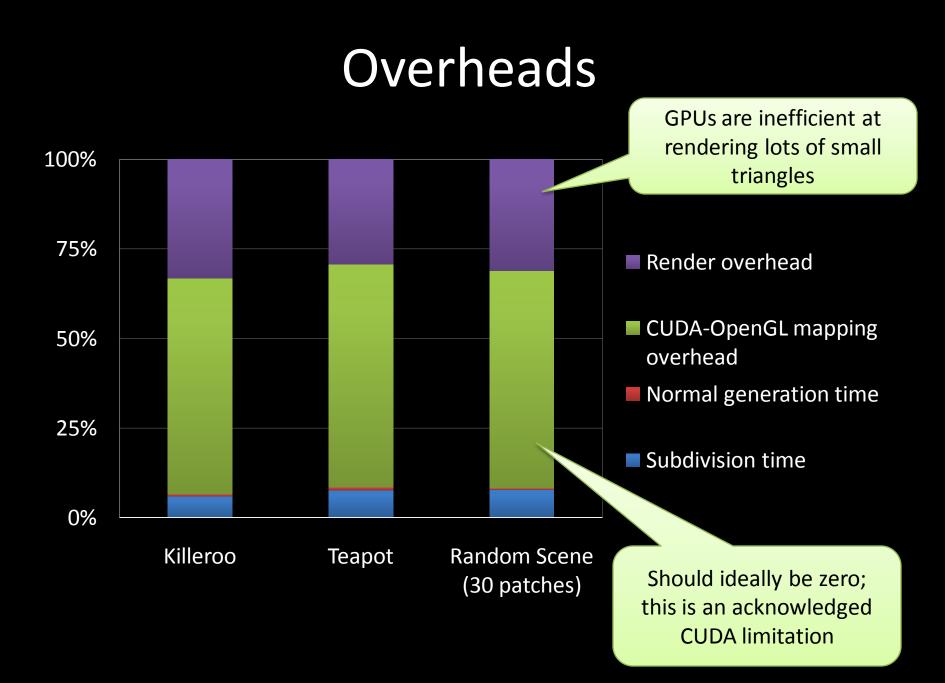
Results - Teapot

- 32 patches → 4823 grids
- 11 levels of subdivision
- Bound/Split: 3.46 ms
- Dice: 2.42 ms
- 12.4 frames per second (subdivision-only: 170)



Results – Random Models



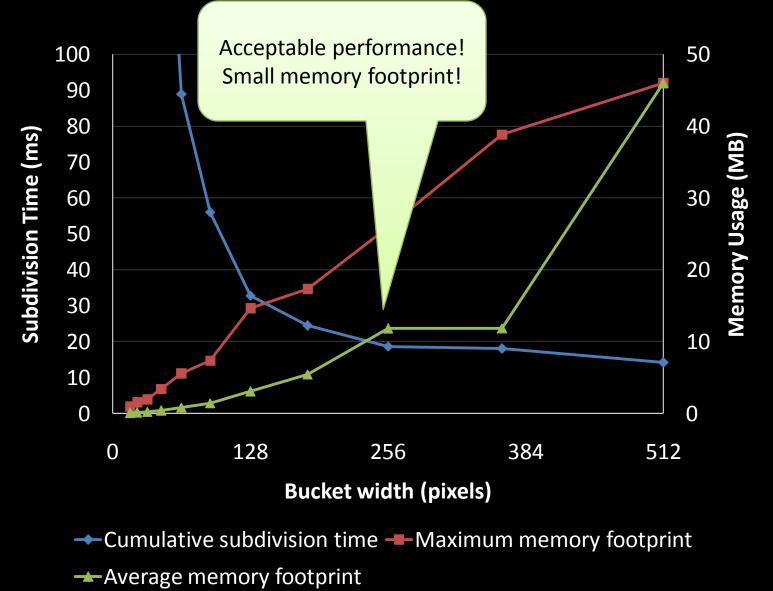


Storage Issues

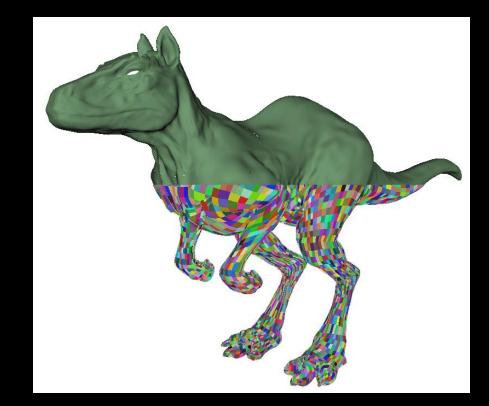
- Reyes pipeline suffers from unbounded memory demand
 - A huge number of micropolygons are generated
 - Transparency and Blending preclude early rejection

- Most implementations use screen-space buckets
 - But how does this work in parallel?
 - Large buckets present a more parallel workload
 - Small buckets have a smaller memory footprint

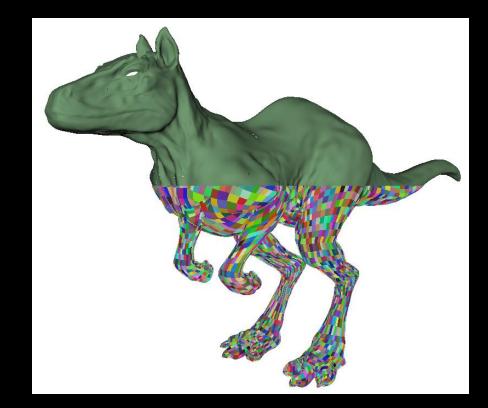
Screen-Space Buckets



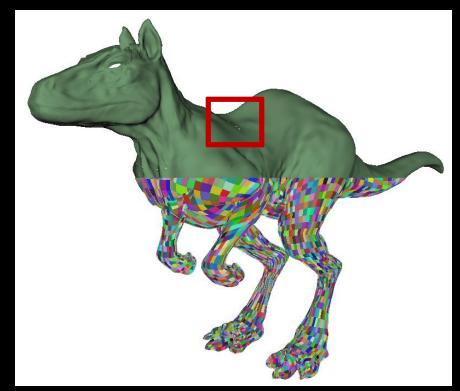
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- Cracks / Pinholes
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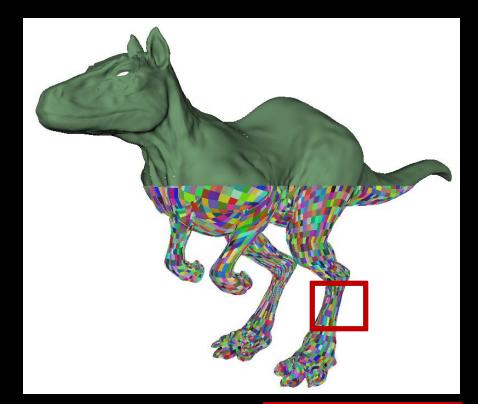


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Conclusions

- Recursive subdivision maps well to current GPUs
 - And works fast!
 - It is advantageous to use smooth primitives in interactive rendering
- Fixed-function tessellation can be emulated
 Dicing is already very fast (2 Mgrids/sec)
- It's time to experiment with alternate pipelines

Future Work

Crack Filling

Add dummy polygons during post-processing

- More of Reyes
 - Displacement Mapping
 - Offline quality Shading on GPUs
 - Parallel Stochastic Sampling (Wei '08)
 - A-buffer

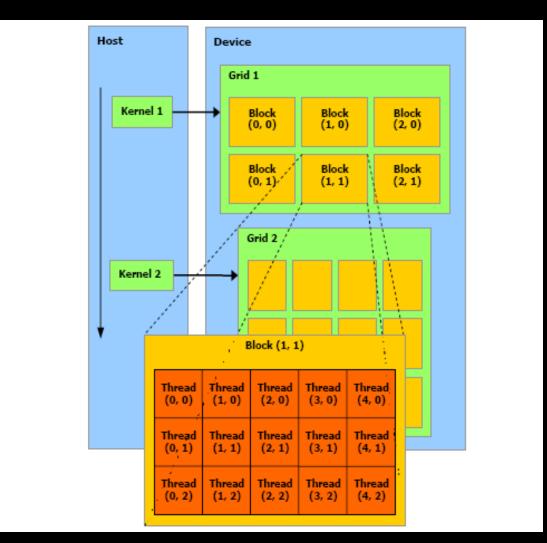
Thanks to

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 - National Science Foundation
 - SciDAC Institute for Ultrascale Visualization
- Equipment support from NVIDIA

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BACKUP SLIDES

CUDA Thread Structure



CUDA Memory Architecture

